Introduction to Programming (in C++)

Numerical algorithms

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Product of polynomials

- Given two polynomials on one variable and real coefficients, compute their product

  (we will decide later how we represent polynomials)

- Example: given $x^2 + 3x - 1$ and $2x - 5$, obtain

  $2x^3 - 5x^2 + 6x^2 - 15x - 2x + 5 = 2x^3 + x^2 - 17x + 5$

Product of polynomials

- Key point:
  Given $p(x) = a_n x^n + a_{n-1} x^{n-1} + \ldots + a_1 x + a_0$
  and $q(x) = b_m x^m + b_{m-1} x^{m-1} + \ldots + b_1 x + b_0$,

  what is the coefficient c_i of x^i in $(p*q)(x)$?

- We obtain x^{i+j} whenever we multiply $a_i\, x^i \cdot b_j\, x^j$

- Idea: for every i and j, add $a_i \cdot b_j$ to the (i+j)-th coefficient of the product polynomial.

Product of polynomials

- Suppose we represent a polynomial of degree *n* by a vector of size *n+1*.

  That is, v[0..n] represents the polynomial

  $$v[n]\, x^n + v[n-1]\, x^{n-1} + \ldots + v[1]\, x + v[0]$$

- We want to make sure that v[v.size() - 1] ≠ 0 so that degree(v) = v.size() - 1

- The only exception is the constant-0 polynomial. We'll represent it by a vector of size 0.

Product of polynomials

```
typedef vector<double> Polynomial;

// Pre: --
// Returns p*q
Polynomial product(const Polynomial& p,
                   const Polynomial& q);
```


Product of polynomials

```
Polynomial product(const Polynomial& p, const Polynomial& q) {

    // Special case for a polynomial of size 0
    if (p.size() == 0 or q.size() == 0) return Polynomial(0);
    else {
        int deg = p.size() – 1 + q.size() - 1; // degree of p*q
        Polynomial r(deg + 1, 0);
        for (int i = 0; i < p.size(); ++i) {
            for (int j = 0; j < q.size(); ++j) {
                r[i + j] = r[i + j] + p[i]*q[j];
            }
        }
        return r;
    }
}

// Invariant (of the outer loop): r = product p[0..i-1]*q
// (we have used the coefficients p[0] … p[i-1])
```


Sum of polynomials

- Note that over the real numbers,

  degree(p*q) = degree(p) + degree(q)

  (except if p = 0 or q = 0).

  So we know the size of the result vector from the start.

- This is not true for the polynomial sum, e.g.

  degree((x + 5) + (-x - 1)) = 0

Sum of polynomials

```
// Pre: --
// Returns p+q
Polynomial sum(const Polynomial& p, const Polynomial& q);
    int maxdeg = max(p.size(), q.size()) - 1;
    int deg = -1;
    Polynomial r(maxdeg + 1, 0);

    // Inv r[0..i-1] = (p+q)[0..i-1] and
    // deg = largest j s.t. r[j] != 0 (or -1 if none exists)
    for (int i = 0; i <= maxdeg; ++i) {
        if (i >= p.size()) r[i] = q[i];
        else if (i >= q.size()) r[i] = p[i];
        else r[i] = p[i] + q[i];
        if (r[i] != 0) deg = i;
    }

    Polynomial rr(deg + 1);
    for (int i = 0; i <= deg; ++i) rr[i] = r[i];
    return rr;
}
```

Sum of sparse vectors

- In some cases, problems must deal with sparse vectors or matrices (most of the elements are zero).
- Sparse vectors and matrices can be represented more efficiently by only storing the non-zero elements. For example, a vector can be represented as a vector of pairs (index, value), sorted in ascending order of the indices.
- Example:

  [0,0,1,0,-3,0,0,0,2,0,0,4,0,0,0]

  can be represented as

  [(2,1),(4,-3),(8,2),(11,4)]

Sum of sparse vectors

- Design a function that calculates the sum of two sparse vectors, where each non-zero value is represented by a pair (index, value):

```
struct Pair {
    int index;
    int value;
}

typedef vector<Pair> SparseVector;
```


Sum of sparse vectors

```
// Pre: --
// Returns v1+v2

SparseVector sparse_sum(const SparseVector& v1,
                        const SparseVector& v2);

// Inv:  p1 and p2 will point to the first
//       non-treated elements of v1 and v2.
//       vsum contains the elements of v1+v2 treated so far.
//       psum points to the first free location in vsum.
```

- Strategy:
  - Calculate the sum on a sufficiently large vector.
  - Copy the result on another vector of appropriate size.

Sum of sparse vectors

```
SparseVector sparse_sum(const SparseVector& v1, const SparseVector& v2) {
  SparseVector vsum;
  int p1 = 0, p2 = 0;

  while (p1 < v1.size() and p2 < v2.size()) {
    if (v1[p1].index < v2[p2].index) { // Element only in v1
      vsum.push_back(v1[p1]);
      ++p1;
    }
    else if (v1[p1].index > v2[p2].index) { // Element only in v2
      vsum.push_back(v2[p2]);
      ++p2;
    }
    else { // Element in both
      Pair p;
      p.index = v1[p1].index;
      p.value = v1[p1].value + v2[p2].value;
      if (p.value != 0) vsum.push_back(p);
      ++p1; ++p2;
    }
  }
```

Sum of sparse vectors

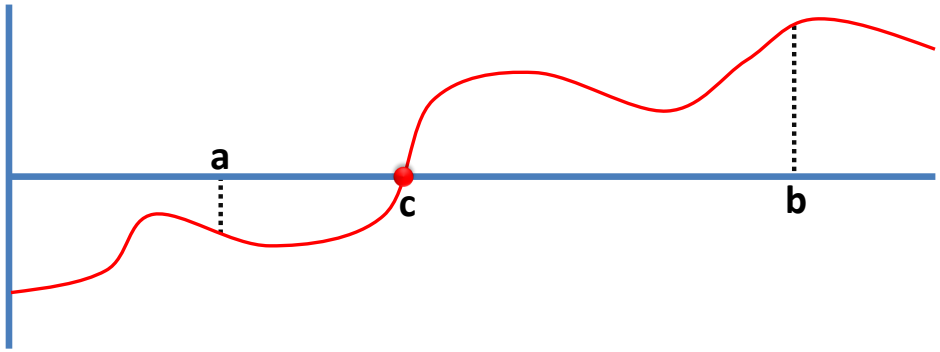
```
    // Copy the remaining elements of v1
    while (p1 < v1.size()) {
        vsum.push_back(v1[p1]);
        ++p1;
    }

    // Copy the remaining elements of v2
    while (p2 < v2.size()) {
        vsum.push_back(v2[p2]);
        ++p2;
    }

    return vsum;
}
```

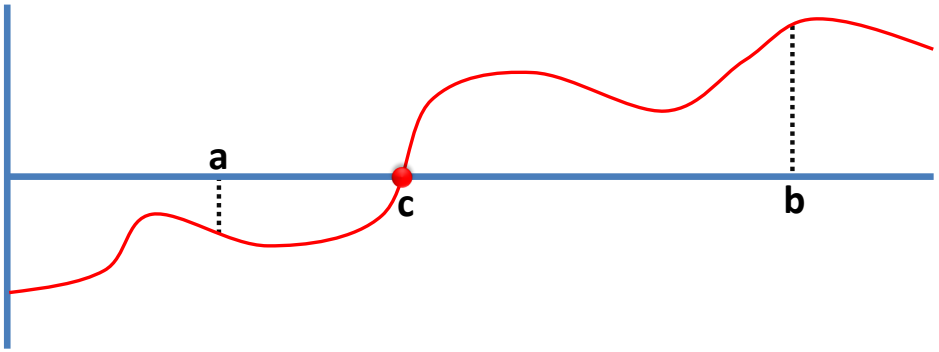

Root of a continuous function

Bolzano's theorem:
Let f be a real-valued continuous function.
Let a and b be two values such that $a < b$ and $f(a) \cdot f(b) < 0$.
Then, there is a value $c \in [a,b]$ such that $f(c)=0$.



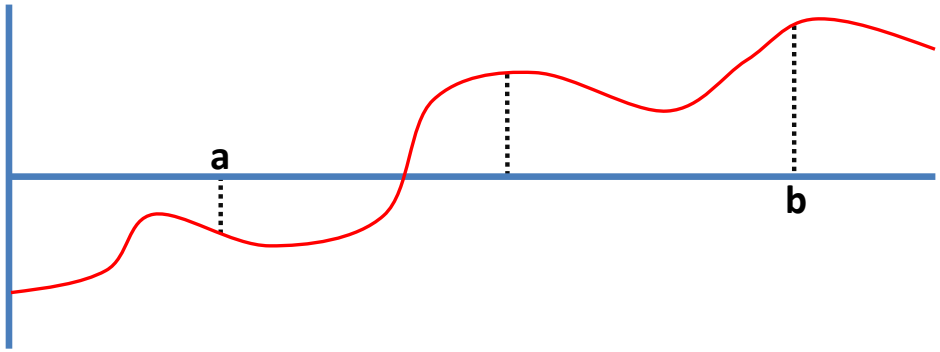
Root of a continuous function

Design a function that finds a root of a continuous function f in the interval $[a, b]$ assuming the conditions of Bolzano's theorem are fulfilled. Given a precision (ε), the function must return a value c such that the root of f is in the interval $[c, c+\varepsilon]$.



Root of a continuous function

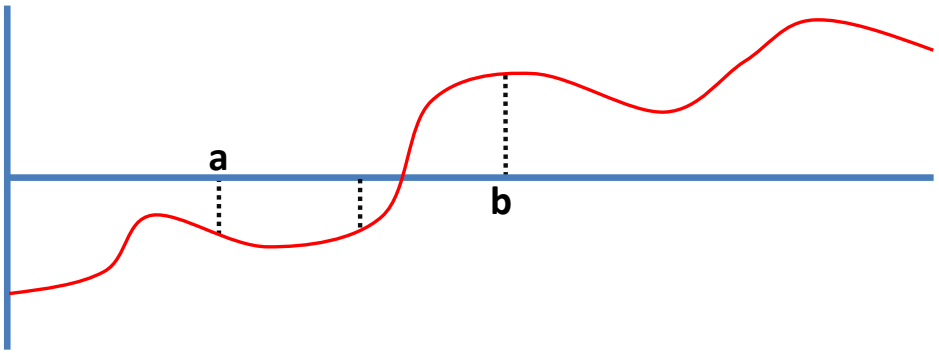
Strategy: narrow the interval $[a, b]$ by half, checking whether the value of f in the middle of the interval is positive or negative. Iterate until the width of the interval is smaller ε.



Root of a continuous function

```
// Pre: f is continuous, a < b and f(a)*f(b) < 0.
// Returns c∈[a,b] such that a root exists in the
// interval [c,c+ε].

// Inv: a root of f exists in the interval [a,b]
```



Root of a continuous function

```
double root(double a, double b, double epsilon) {
    while (b – a > epsilon) {
        double c = (a + b)/2;
        if (f(a)*f(c) <= 0) b = c;
        else a = c;
    }
    return a;
}
```


Root of a continuous function

```
// A recursive version

double root(double a, double b, double epsilon) {
    if (b – a <= epsilon) return a;
    double c = (a + b)/2;
    if (f(a)*f(c) <= 0) return root(a,c,epsilon);
    else return root(c,b,epsilon);
}
```


Barcode

- A barcode is an optical machine-readable representation of data. One of the most popular encoding systems is the UPC (Universal Product Code).
- A UPC code has 12 digits. Optionally, a check digit can be added.

Barcode

- The check digit is calculated as follows:
  1. Add the digits in odd-numbered positions (first, third, fifth, etc.) and multiply by 3.
  2. Add the digits in the even-numbered positions (second, fourth, sixth, etc.) to the result.
  3. Calculate the result modulo 10.
  4. If the result is not zero, subtract the result from 10.

- Example: 380006571113
  - (3+0+0+5+1+1)*3 = 30
  - 8+0+6+7+1+3 = 25
  - (30+25) mod 10 = 5
  - 10 – 5 = **5**

Barcode

- Design a program that reads a sequence of 12-digit numbers that represent UPCs without check digits and writes the same UPCs with the check digit.

- Question: do we need a data structure to store the UPCs?

- Answer: no, we only need a few auxiliary variables.

Barcode

- The program might have a loop treating a UPC at each iteration. The invariant could be as follows:

```
// Inv: all the UPCs of the treated codes
//      have been written.
```

- At each iteration, the program could read the UPC digits and, at the same time, write the UPC and calculate the check digit. The invariant could be:

```
// Inv: all the treated digits have been
//      written. The partial calculation of
//      the check digit has been performed
//      based on the treated digits.
```


Barcode

```
// Pre:  the input contains a sequence of UPCs without check digits.
// Post: the UPCs at the input have been written with their check digits.

int main() {
    char c;
    while (cin >> c) {
        cout << c;
        int d = 3*(int(c) - int('0')); // first digit in an odd location
        for (int i = 2; i <= 12; ++i) {
             cin >> c;
             cout << c;
             if (i%2 == 0) d = d + int(c) - int('0');
             else d = d + 3*(int(c) - int('0'));
        }
        d = d%10;
        if (d > 0) d = 10 – d;
        cout << d << endl;
    }
}
```