## What do we expect from an algorithm?

- Correct


## Algorithm Analysis (I)

Jordi Cortadella and Jordi Petit
Department of Computer Science

- Easy to understand
- Easy to implement
- Efficient:
- Every algorithm requires a set of resources
- Memory
- CPU time
- Energy

Fibonacci: recursive version

```
def fib(n: int) -> int:
    """Returns the Fibonacci number of order n
        Pre: n \geq 0
    if n <= 1:
        return n
    return fib(n-1) + fib(n - 2)
```

$$
\begin{aligned}
& T(0)=1 \\
& T(1)=1 \\
& T(n)=T(n-1)+T(n-2)
\end{aligned}
$$

Let us assume that $T(n)=a^{n}$ for some constant $a$. Then,

$$
\begin{array}{rlrl}
a^{n} & =a^{n-1}+a^{n-2} \quad \Rightarrow & a^{2}=a+1 \\
a & =\frac{1+\sqrt{5}}{2}=\varphi \approx 1.618 & & \text { (golden ratio) }
\end{array}
$$

Therefore, $T(n) \approx 1.6^{n}$. If $T(0)=1 \mathrm{~ns}$, then $T(100) \approx 2.6 \cdot 10^{20} \mathrm{~ns}>8000 \mathrm{yrs}$.
With the age of Universe $\left(14 \cdot 10^{9} \mathrm{yrs}\right)$, we could compute up to fib(128).

```
def fib(n: int) -> int:
    """Returns the Fibonacci number of order n
        Pre: n \geq0
    *
    f_i, f_i1 = 0, 1
    # Inv: f_i is the Fibonacci number of order i
    # f_i1 is the Fibonacci number of order i+1
    for i in range(n):
        f_i, f_i1 = f_i1, f_i+f_i1
    return f_i
```

Runtime: $\mathbf{n}$ iterations

## Fibonacci numbers

Algebraic solution: find matrix $A$ such that

$$
\begin{gathered}
{\left[\begin{array}{l}
F_{n+2} \\
F_{n+1}
\end{array}\right]=\left[\begin{array}{ll}
? & ? \\
? & ?
\end{array}\right] \cdot\left[\begin{array}{c}
F_{n+1} \\
F_{n}
\end{array}\right]} \\
{\left[\begin{array}{c}
F_{n+2} \\
F_{n+1}
\end{array}\right]=\left[\begin{array}{ll}
1 & 1 \\
1 & 0
\end{array}\right] \cdot\left[\begin{array}{c}
F_{n+1} \\
F_{n}
\end{array}\right]} \\
{\left[\begin{array}{c}
F_{n+1} \\
F_{n}
\end{array}\right]=A^{n} \cdot\left[\begin{array}{l}
1 \\
0
\end{array}\right]}
\end{gathered}
$$

$$
\begin{array}{cc}
A^{1}=\left[\begin{array}{ll}
1 & 1 \\
1 & 0
\end{array}\right] & A^{2}=\left[\begin{array}{ll}
2 & 1 \\
1 & 1
\end{array}\right] \\
A^{4}=\left[\begin{array}{ll}
5 & 3 \\
3 & 2
\end{array}\right] & A^{8}=\left[\begin{array}{ll}
34 & 21 \\
21 & 13
\end{array}\right] \\
A^{16}=\left[\begin{array}{cc}
1597 & 987 \\
987 & 610
\end{array}\right] & \cdots A^{n}=\left[\begin{array}{cc}
F_{n+1} & F_{n} \\
F_{n} & F_{n-1}
\end{array}\right]
\end{array}
$$

Runtime $\approx \log _{2} n 2 \times 2$ matrix multiplications

## Algorithm analysis

## Algorithm analysis: simplifications

Given an algorithm that reads inputs from a domain $D$, we want to define a cost function $C$ :

$$
\begin{aligned}
C: D & \rightarrow \mathbb{R}^{+} \\
x & \mapsto C(x)
\end{aligned}
$$

where $C(x)$ represents the cost of using some resource (CPU time, memory, energy, ...).
Analyzing $C(x)$ for every possible $x$ is impractical.

## Algorithm analysis

- Properties:

$$
\begin{array}{ll}
\forall n \geq 0: & C_{\text {best }}(n) \leq C_{\text {avg }}(n) \leq C_{\text {worst }}(n) \\
\forall x \in D: & C_{\text {best }}(|x|) \leq C(x) \leq C_{\text {worst }}(|x|)
\end{array}
$$

- We want a notation that characterizes the cost of algorithms independently from the technology (CPU speed, programming language, efficiency of the compiler, etc.).
- Runtime is usually the most important resource to analyze.
- Analysis based on the size of the input: $|x|=n$
- Only the best/average/worst cases are analyzed:

$$
\begin{aligned}
C_{\text {worst }}(n) & =\max \{C(x): x \in D,|x|=n\} \\
C_{\text {best }}(n) & =\min \{C(x): x \in D,|x|=n\} \\
C_{\text {avg }}(n) & =\sum_{x \in D,|x|=n} p(x) \cdot C(x)
\end{aligned}
$$

$p(x)$ : probability of selecting input $x$ among all the inputs of size $n$.

## Asymptotic notation

Let us consider all functions $f: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$

Definitions:

$$
\begin{aligned}
& \mathrm{O}(f(n))=\left\{g(n): \exists k>0, \exists n_{0}, \forall n \geq n_{0}: g(n) \leq k \cdot f(n)\right\} \\
& \Omega(f(n))=\left\{g(n): \exists k>0, \exists n_{0}, \forall n \geq n_{0}: g(n) \geq k \cdot f(n)\right\} \\
& \Theta(f(n))=\mathrm{O}(f(n)) \cap \Omega(f(n))
\end{aligned}
$$



$$
\begin{aligned}
& g(n) \in \mathrm{O}\left(f_{1}(n)\right) \\
& g(n) \in \Omega\left(f_{2}(n)\right)
\end{aligned}
$$

## Asymptotic notation: example



$$
\begin{aligned}
\Theta\left(n^{2}\right)=\mathrm{O}\left(n^{2}\right) \cap \Omega\left(n^{2}\right)= & \left\{3 n^{2}-n+20,\right. \\
& 0.5 n^{2}-3, \\
& n<20 ? 2^{n}: 2 n^{2}+1000, \\
& \cdots \\
& \}
\end{aligned}
$$


$g(n) \in \Theta(f(n))$
© Dept. CS, UPC

## Examples

Big- $\Omega$

| $13 n^{3}-4 n+8$ | $\in$ | $\mathrm{O}\left(n^{3}\right)$ |
| :---: | :---: | :---: |
| $2 n-5$ | $\in$ | $\mathrm{O}(n)$ |
| $n^{2}$ | $\notin$ | $\mathrm{O}(n)$ |
| $2^{n}$ | $\in$ | $\mathrm{O}(n!)$ |
| $3^{n}$ | $\notin$ | $\mathrm{O}\left(2^{n}\right)$ |
| $3 \log _{2} n$ | $\in$ | $\mathrm{O}(\log n)$ |
| $n \log _{2} n$ | $\in$ | $\mathrm{O}\left(n^{2}\right)$ |
| $\mathrm{O}\left(n^{2}\right)$ | $\subseteq$ | $\mathrm{O}\left(n^{3}\right)$ |


| $13 n^{3}-4 n+8$ | $\in$ | $\Omega\left(n^{3}\right)$ |
| :---: | :---: | :---: |
| $n^{2}$ | $\in$ | $\Omega(n)$ |
| $n^{2}$ | $\notin$ | $\Omega\left(n^{3}\right)$ |
| $n!$ | $\in$ | $\Omega\left(2^{n}\right)$ |
| $3^{n}$ | $\notin$ | $\Omega\left(2^{n}\right)$ |
| $3 \log _{2} n$ | $\in$ | $\Omega(\log n)$ |
| $n \log _{2} n$ | $\in$ | $\Omega(n)$ |
| $\Omega\left(n^{3}\right)$ | $\subseteq$ | $\Omega\left(n^{2}\right)$ |

## Complexity ranking

| Function | Common name |
| :--- | :--- |
| $n!$ | factorial |
| $2^{n}$ | exponential |
| $n^{d}, d>3$ | polynomial |
| $n^{3}$ | cubic |
| $n^{2}$ | quadratic |
| $n \sqrt{n}$ |  |
| $n \log n$ | quasi-linear |
| $n$ | linear |
| $\sqrt{n}$ | root - $n$ |
| $\log n$ | logarithmic |
| 1 | constant |

Let us assume that $L$ exists (may be $\infty$ ) such that:

$$
\begin{aligned}
& L=\lim _{n \rightarrow \infty} \frac{f(n)}{g(n)} \\
& \left\{\begin{array}{lll}
\text { if } L=0 & \text { then } & f \in \mathrm{O}(g) \\
\text { if } 0<L<\infty & \text { then } & f \in \Theta(g) \\
\text { if } L=\infty & \text { then } & f \in \Omega(g)
\end{array}\right.
\end{aligned}
$$

Note: If both limits are $\infty$ or 0 , use L'Hôpital rule:

$$
\lim _{x \rightarrow \infty} \frac{f(x)}{g(x)}=\lim _{x \rightarrow \infty} \frac{f^{\prime}(x)}{g^{\prime}(x)}
$$

## Properties

## Asymptotic complexity (small values)

- $f \in O(f)$
- $\forall c>0, \quad \mathrm{O}(f)=\mathrm{O}(c \cdot f)$
- $f \in \mathrm{O}(g) \wedge g \in \mathrm{O}(h) \Rightarrow f \in \mathrm{O}(h)$
- $f_{1} \in O\left(g_{1}\right) \wedge f_{2} \in O\left(g_{2}\right)$

$$
\Rightarrow f_{1}+f_{2} \in \mathrm{O}\left(g_{1}+g_{2}\right)=\mathrm{O}\left(\max \left\{g_{1}, g_{2}\right\}\right)
$$

- $f \in \mathrm{O}(g) \Rightarrow f+g \in \mathrm{O}(g)$
- $f_{1} \in \mathrm{O}\left(g_{1}\right) \wedge f_{2} \in \mathrm{O}\left(g_{2}\right) \Rightarrow f_{1} \cdot f_{2} \in \mathrm{O}\left(g_{1} \cdot g_{2}\right)$
- $f \in O(g) \Leftrightarrow g \in \Omega(f)$




## How about "big data"?

Source: Jon Kleinberg and Éva Tardos, Algorithm Design, Addison Wesley 2006.

Table 2.1 The running times (rounded up) of different algorithms on inputs of increasing size, for a processor performing a million high-level instructions per second. In cases where the running time exceeds $10^{25}$ years, we simply record the algorithm as taking a very long time.

|  |  | Table 2. increasin In cases taking a | The runnin ize, for a p ere the run $y$ long tim | times (round cessor perforn ng time excee | up) of differen a million high $10^{25}$ years, we s | algorithms on vel instructio ply record th | inputs of per second. gorithm as |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $n$ | $n \log _{2} n$ | $n^{2}$ | $n^{3}$ | $1.5{ }^{n}$ | $2^{n}$ | $n!$ |
| $n=10$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 4 sec |
| $n=30$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 18 min | $10^{25}$ years |
| $n=50$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 11 min | 36 years | very long |
| $n=100$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 1 sec | 12,892 years | $10^{17}$ years | very long |
| $n=1,000$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 1 sec | 18 min | very long | very long | very long |
| $n=10,000$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 2 min | 12 days | very long | very long | very long |
| $n=100,000$ | $<1 \mathrm{sec}$ | 2 sec | 3 hours | 32 years | very long | very long | very long |
| $n=1,000,000$ | 1 sec | 20 sec | 12 days | 31,710 years | very long | very long | very long |

[^0]Let us consider that every operation can be executed in $1 \mathrm{~ns}\left(10^{-9} \mathrm{~s}\right)$.

|  | Time |  |  |
| :--- | ---: | ---: | ---: |
| Function | $n=1,000$ | $n=10,000$ | $n=100,000$ |
| $\log _{2} n$ | 10 ns | 13.3 ns | 16.6 ns |
| $\sqrt{n}$ | 31.6 ns | 100 ns | 316 ns |
| $n$ | $1 \mu \mathrm{~s}$ | $10 \mu \mathrm{~s}$ | $100 \mu \mathrm{~s}$ |
| $n \log _{2} n$ | $10 \mu \mathrm{~s}$ | $133 \mu \mathrm{~s}$ | 1.7 ms |
| $n^{2}$ | 1 ms | 100 ms | 10 s |
| $n^{3}$ | 1 s | 16.7 min | 11.6 days |
| $n^{4}$ | 16.7 min | 116 days | 3171 yr |
| $2^{n}$ | $3.4 \cdot 10^{284} \mathrm{yr}$ | $6.3 \cdot 10^{2993} \mathrm{yr}$ | $3.2 \cdot 10^{30086} \mathrm{yr}$ |

## The robot and the door in an infinite wall

A robot stands in front of a wall that is infinitely long to the right and left side.
The wall has a door somewhere and the robot has to find it to reach the other side. Unfortunately, the robot can only see the part of the wall in front of it.

The robot does not know neither how far away the door is nor what direction to take to find it. It can only execute moves to the left or right by a certain number of steps.

Let us assume that the door is at a distance $d$. How to find the door in a minimum number of steps?


## Algorithm 1:

- Pick one direction and move until the door is found.


## Complexity:

- If the direction is correct $\rightarrow \mathrm{O}(d)$.
- If incorrect $\rightarrow$ the algorithm does not terminate.

The robot and the door in an infinite wall

## Algorithm 2:

- 1 step to the left,
- 2 steps to the right,
- 3 steps to the left, ...
- ... increasing by one step in the opposite direction.


## Complexity:

$$
T(d)=3 d+\sum_{i=1}^{d-1} 4 i=3 d+4 \frac{d(d-1)}{2}=2 d^{2}+d=0\left(d^{2}\right)
$$

Algorithm Analysis
The robot and the door in an infinite wall


## Algorithm 3:

- 1 step to the left and return to origin,
- 2 steps to the right and return to origin,
- 3 steps to the left and return to origin,...
- ... increasing by one step in the opposite direction.


## Complexity:

$$
T(d)=d+\sum_{i=1}^{d} 2 i=d+2 \frac{d(d+1)}{2}=d^{2}+2 d=0\left(d^{2}\right)
$$

## Algorithm 4:

- 1 step to the left and return to origin,
- 2 steps to the right and return to origin,
- 4 steps to the left and return to origin,...
- ... doubling the number of steps in the opposite direction.

Complexity (assume that $d=2^{n}$ ):

$$
T(d)=d+2 \sum_{i=0}^{n} 2^{i}=d+2\left(2^{n+1}-1\right)=5 d-2=0(d)
$$

- Variable declarations cost no time.
- Elementary operations are those that can be executed with a small number of basic computer steps (an assignment, a multiplication, a comparison between two numbers, etc.).
- Vector sorting or matrix multiplication are not elementary operations.
- We consider that the cost of elementary operations is $0(1)$.
- Consecutive statements:
- If $S 1$ is $O(f)$ and $S 2$ is $O(g)$, then $\mathrm{S} 1 ; \mathrm{S} 2$ is $\mathrm{O}(\max \{f, g\})$
- Conditional statements:
- If S 1 is $\mathrm{O}(f), \mathrm{S} 2$ is $\mathrm{O}(g)$ and B is $\mathrm{O}(h)$, then if ( B$) \mathrm{S} 1$; else S 2 ; is $\mathrm{O}(\max \{f+h, g+h\})$, or also $O(\max \{f, g, h\})$.

Runtime analysis rules

- For/While loops:
- Running time is at most the running time of the statements inside the loop times the number of iterations
- Nested loops:
- Analyze inside out: running time of the statements inside the loops multiplied by the product of the sizes of the loops

```
for i in range(n):
    for j in range(n)
        do_something() # O(1)
for i in range(n):
    for j in range(i, n):
        OO(n}\mp@subsup{n}{}{2}
        do_something() # O(1)
for i in range(n):
    for j in range(m):
        \Longrightarrow \mathrm { O } ( n \cdot m \cdot p )
        for k in range(p):
            do_something() # O(1)
```

Running time proportional to input size

```
# Compute the maximum of a vector with n numbers
m = a[0]
for i in range(1, len(a)):
    m = max(m, a[i])
# Equivalent way in Python (same complexity)
m = max(a)
```


## Other examples:

- Reversing a vector
- Merging two sorted vectors
- Finding the largest null segment of a sorted vector: a linear-time algorithm exists
(a null segment is a compact sub-vector in which the sum of all the elements is zero)


## Logarithmic time: $O(\log n)$

- Logarithmic time is usually related to divide-and-conquer algorithms
- Examples:
- Binary search
- Calculating $x^{n}$
- Calculating the $n$-th Fibonacci number

$$
\begin{aligned}
& T\left(x^{y}\right) \leq 4+T\left(\left(x^{2}\right)^{y / 2}\right) \leq 4+4+T\left(\left(x^{4}\right)^{y / 4}\right) \leq \cdots \\
& T\left(x^{y}\right) \leq \underbrace{4+4+\cdots+4}_{\log _{2} y \text { times }} \Longrightarrow \mathrm{O}(\log y)
\end{aligned}
$$

Linearithmic time: $O(n \log n)$

- Sorting: Merge sort and heap sort can be executed in $0(n \log n)$.
- Largest empty interval: Given $n$ time-stamps $x_{1}, \cdots, x_{n}$ on which copies of a file arrive at a server, what is largest interval when no copies of file arrive?
$-O(n \log n)$ solution. Sort the time-stamps. Scan the sorted list in order, identifying the maximum gap between successive time-stamps.


[^0]:    This is often the practical limit for big data

