## Mathematical Logic and Linguistics

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> BGSMath Course Class 5

Recall the following operations on sets:

(1) a. Functional exponentiation:

 $X^{Y}$  = the set of all total functions from Y to X

b. Cartesian product:  $X \times Y = \{\langle x, y \rangle | x \in X \& y \in Y\}$ 

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- c. Disjoint union:  $X \uplus Y = (\{1\} \times X) \cup (\{2\} \times Y)$
- d. *n*-th Cross product,  $n \in \mathcal{N}$ :  $X^0 = \{0\}$  $X^{1+n} = X \times (X^n)$

The set  $\mathcal{T}$  of *semantic types* of the semantic representation language is defined on the basis of a set  $\delta$  of *basic semantic types* as follows:

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(2)  $\mathcal{T} ::= \delta \mid \top \mid \mathcal{T} + \mathcal{T} \mid \mathcal{T} \& \mathcal{T} \mid \mathcal{T} \to \mathcal{T} \mid \mathsf{M}\mathcal{T} \mid \mathsf{L}\mathcal{T} \mid \mathcal{T}^+$ 

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A semantic frame comprises a family  $\{D_{\tau}\}_{\tau \in \delta}$  of non-empty basic type domains and a nonempty set W of worlds. This induces a nonempty type domain  $D_{\tau}$  for each type  $\tau$  as follows:

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$$\begin{array}{rcl} (5) & D_{\mathsf{T}} & = & \{\emptyset\} \\ & D_{\tau_1 + \tau_2} & = & D_{\tau_1} \uplus D_{\tau_2} \\ & D_{\tau_1 \& \tau_2} & = & D_{\tau_1} \times D_{\tau_2} \\ & D_{\tau_1 \to \tau_2} & = & D_{\tau_2}^{D_{\tau_1}} \\ & D_{\mathsf{M}\tau} & = & \mathsf{W} \times D_{\tau} \\ & D_{\mathsf{L}\tau} & = & D_{\tau}^W \\ & D_{\tau^+} & = & \bigcup_{n > 0} (D_{\tau})^n \end{array}$$

## Semantic Representation Language

The sets  $\Phi_{\tau}$  of *terms* of type  $\tau$  for each semantic type  $\tau$  are defined on the basis of sets  $C_{\tau}$  of constants of type  $\tau$  and denumerably infinite sets  $V_{\tau}$  of variables of type  $\tau$  for each type  $\tau$  as follows:

(6)

$$\begin{array}{rcl} \Phi_{\tau} & ::= & C_{\tau} \\ \Phi_{\tau} & ::= & V_{\tau} \\ \Phi_{\tau} & ::= & 0 \\ \Phi_{\tau} & ::= & \Phi_{\tau_1+\tau_2} -> V_{\tau_1} \cdot \Phi_{\tau}; \ V_{\tau_2} \cdot \Phi_{\tau} \\ \Phi_{\tau+\tau'} & ::= & \iota_1 \Phi_{\tau} \\ \Phi_{\tau'+\tau} & ::= & \iota_2 \Phi_{\tau} \\ \Phi_{\tau} & ::= & \pi_1 \Phi_{\tau \& \tau'} \\ \Phi_{\tau} & ::= & \pi_2 \Phi_{\tau' \& \tau} \\ \Phi_{\tau \& \tau'} & ::= & (\Phi_{\tau}, \Phi_{\tau'}) \\ \Phi_{\tau} & ::= & (\Phi_{\tau' \to \tau} \Phi_{\tau'}) \\ \Phi_{\tau \to \tau'} & ::= & \lambda V_{\tau} \Phi_{\tau'} \\ \Phi_{\tau} & ::= & ^{\wedge} \Phi_{\tau} \\ \Phi_{\tau} & ::= & ^{\wedge} \Phi_{\tau} \\ \Phi_{\pi} & ::= & ^{\wedge} \Phi_{\tau} \\ \Phi_{\tau^+} & ::= & [\Phi_{\tau}] \mid [\Phi_{\tau} \mid \Phi_{\tau^+}] \end{array}$$

case statement first injection second injection first projection second projection ordered pair formation functional application functional abstraction extensionalization intensionalization projection injection non-empty list construction Given a semantic frame, a *valuation f* mapping each constant of type  $\tau$  into an element of  $D_{\tau}$ , an assignment *g* mapping each variable of type  $\tau$  into an element of  $D_{\tau}$ , and a world  $i \in W$ , each term  $\phi$  of type  $\tau$  receives an interpretation  $[\phi]^{g,i} \in D_{\tau}$  as shown below;

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In  $x.\phi$ ,  $\lambda x\phi$  or  $\wedge \phi$ ,  $\phi$  is the *scope* of x.,  $\lambda x$  or  $\wedge$ .

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An occurrence of a variable x in a term is called *free* if and only if it does not fall within the scope of any x. or  $\lambda x$ ; otherwise it is *bound* (by the closest x. or  $\lambda x$  within the scope of which it falls).

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The result  $\phi\{\psi_1/x_1, \dots, \psi_n/x_n\}$  of substituting terms  $\psi_1, \dots, \psi_n$  for variables  $x_1, \dots, x_n$  of the same types respectively in a term  $\phi$  is the result of simultaneously replacing by  $\psi_i$  every free occurrence of  $x_i$  in  $\phi$ .

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We say that  $\psi$  is free for x in  $\phi$  if and only if no variable in  $\psi$  becomes bound in  $\phi{\{\psi/x\}}$ .

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There are the following laws of conversion.

 $\iota_1 \phi \rightarrow y.\psi; z.\chi = \psi \{\phi/y\}$ if  $\phi$  is free for y in  $\psi$  and modally free for y in  $\psi$  $\iota_2 \phi \rightarrow y.\psi; z.\chi = \chi\{\phi/z\}$ if  $\phi$  is free for z in  $\chi$  and modally free for z in  $\chi$  $\begin{array}{rcl} \pi_1(\phi,\psi) &=& \phi \\ \pi_2(\phi,\psi) &=& \psi \end{array}$  $(\lambda x \phi \psi) = \phi \{\psi/x\}$ if  $\psi$  is free for x in  $\phi$ , and modally free for x in  $\phi$  $\overset{\vee \wedge \phi}{\overset{\cup}{\phantom{}}} = \phi$ β-conversion  $\begin{array}{rcl} (\pi_1\phi,\pi_2\phi) &=& \phi\\ \lambda x(\phi\,x) &=& \phi \end{array}$ if x is not free in  $\phi$  $^{\wedge\vee}\phi \quad = \quad \phi$ if  $\phi$  is modally closed  $^{\cap \cup}\phi \quad = \quad \phi$ n-conversion

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For completeness, the so-called commuting conversions for the case statement are thus:

$$\begin{array}{rcl} \phi -> x.\iota_1\psi; y.\iota_1\chi &=& \iota_1(\phi -> x.\psi; y.\chi) \\ \phi -> x.\iota_2\psi; y.\iota_2\chi &=& \iota_2(\phi -> x.\psi; y.\chi) \\ \phi -> x.\pi_1\psi; y.\iota_1\chi &=& \pi_1(\phi -> x.\psi; y.\chi) \\ \phi -> x.\pi_2\psi; y.\iota_2\chi &=& \pi_2(\phi -> x.\psi; y.\chi) \\ \phi -> x.(\delta,\psi); y.(\delta,\chi) &=& (\delta,\phi -> x.\psi; y.\chi) \\ \phi -> x.(\phi,\delta); y.(\chi,\delta) &=& (\phi -> x.\psi; y.\chi,\delta) \\ \phi -> x.(\delta\psi); y.(\delta\chi) &=& (\delta\phi -> x.\psi; y.\chi) \\ \phi -> x.(\psi,\delta); y.(\chi,\delta) &=& (\phi -> x.\psi; y.\chi) \\ \phi -> x.(\psi,\delta); y.(\chi,\delta) &=& (\phi -> x.\psi; y.\chi) \\ \end{array}$$

$$\phi \rightarrow x.\lambda z\psi; y.\lambda z\chi = \lambda z(\phi \rightarrow x.\psi; y.\chi)$$
  
if z is not free in  $\phi$ 

$$\phi \rightarrow \mathbf{x}.^{\vee}\psi; \mathbf{y}.^{\vee}\chi = ^{\vee}(\phi \rightarrow \mathbf{x}.\psi; \mathbf{y}.\chi)$$

$$\phi \rightarrow x.^{\psi}; y.^{\chi} = (\phi \rightarrow x.\psi; y.\chi)$$
  
if  $\phi$  is modally closed

$$\begin{array}{rcl} \phi -> \mathbf{x}.^{\cup}\psi; \mathbf{y}.^{\cup}\chi &=& {}^{\cup}(\phi -> \mathbf{x}.\psi; \mathbf{y}.\chi) \\ \phi -> \mathbf{x}.^{\cap}\psi; \mathbf{y}.^{\cap}\chi &=& {}^{\cap}(\phi -> \mathbf{x}.\psi; \mathbf{y}.\chi) \\ \phi -> \mathbf{x}.[\delta|\psi]; \mathbf{y}.[\delta|\chi] &=& [\delta|\phi -> \mathbf{x}.\psi; \mathbf{y}.\chi] \\ \phi -> \mathbf{x}.[\psi|\delta]; \mathbf{y}.[\chi|\delta] &=& [\phi -> \mathbf{x}.\psi; \mathbf{y}.\chi|\delta] \end{array}$$